

# IEEE World AI IoT 2022 IoT Workshop

## WINDOWS GETTING RASPBERRY PI IMAGES

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### SUMMARY

This document shows how to download a Raspberry Pi image. It also shows how to run a Raspberry Pi image using qemu-system-arm.

### DETAILS

Each step in Part 2 works to get images of Raspberry Pis working on your machine. These steps discuss some technical details of virtual Raspberry Pis using QEMU. These steps should be completed at least one day before the workshop. All these installations and downloads are at your own risk.

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## STEPS

Step 1 requires git to be installed. If you do not have it installed already, then please see the accompanying document: **Part 2 Windows Install GIT.pdf**

Or go to: <https://github.com/git-guides/install-git>

### STEP 1: CREATE FOLDERS ON YOUR WINDOWS MACHINE

On Windows these folders can be created using the **File Explorer** or a **Command Prompt (Terminal)**.

Our objective is to build the following folders

Folder	Commands
<b>C:\users\your-id\workshop</b>	cd . ; mkdir workshop
<b>~/workshop/RPi1</b>	git clone https://github.com/wonder-phil/RPi
<b>~/workshop/RPi2</b>	After images are in RPi1 then duplicate RPi1 to RPi2
<b>~/workshop/code</b>	git clone

Assuming your-id is your login-id on your Windows 10 or 11 machine, then here are the Terminal commands to create the folders:

**Windows>** cd

**Windows>** mkdir workshop

**Windows>** cd workshop

**Windows>** git clone https://github.com/wonder-phil/RPi

**Windows>** dir /a RPi

3.2M Jul 14 12:40 gemukernel

7.9K Jul 14 12:39 versatile-pb.dtb

These two files are in your workshop/RPi folder

The gemukernel file is the Raspberrian operating system.

The versatile-pb.dtb is a mother board emulated by QEMU. Technically these are ARM Versatile/PB (ARM926EJ-S). Others are available as well.

#### STEP 2: DOWNLOAD RASPBERRY PI IMG

<https://www.raspberrypi.org/software/operating-systems/>

Download Paspberry Pi OS Lite (438MB), 11-January-2021 or later

Download **the Raspberry Pi OS Lite** image as shown below:

## Raspberry Pi OS with desktop and recommended software

Release date: December 2nd 2020

Kernel version: 5.4

Size: 2,949MB

[Show SHA256 file integrity hash:](#)

[Release notes](#)

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## Raspberry Pi OS with desktop

Release date: December 2nd 2020

Kernel version: 5.4

Size: 1,177MB

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[Release notes](#)

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## Raspberry Pi OS Lite

Release date: December 2nd 2020

Kernel version: 5.4

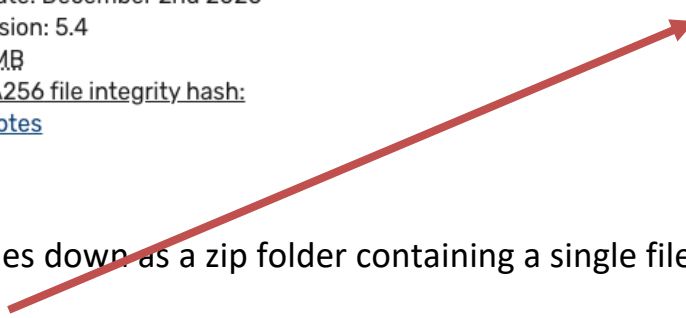
Size: 438MB

[Show SHA256 file integrity hash:](#)

[Release notes](#)

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This comes down as a zip folder containing a single file. Unzip this folder getting the file: 

**2021-01-11-raspios-buster-armhf-lite.img**

Place this file in ~/workshop/RPi

**Windows>** cd ~/workshop/RPi

**Windows>** dir

1.7G Mar 3 07:56 2021-01-11-raspios-buster-armhf-lite.img  
3.2M Jul 14 12:40 qemukernel  
7.9K Jul 14 12:39 versatile-pb.dtb

### STEP 3: RUN A RASPBERRY PI QEMU VIRTUAL MACHINE

**Windows>** cd ~/workshop/RPi

Check the IMG file:

**Windows>** qemu-img info 2021-01-11-raspios-buster-armhf-lite.img

image: 2021-01-11-raspios-buster-armhf-lite.img  
file format: raw  
virtual size: 1.73 GiB (1858076672 bytes)  
disk size: 1.73 GiB

Now convert the IMG file to a QCOW2 file:

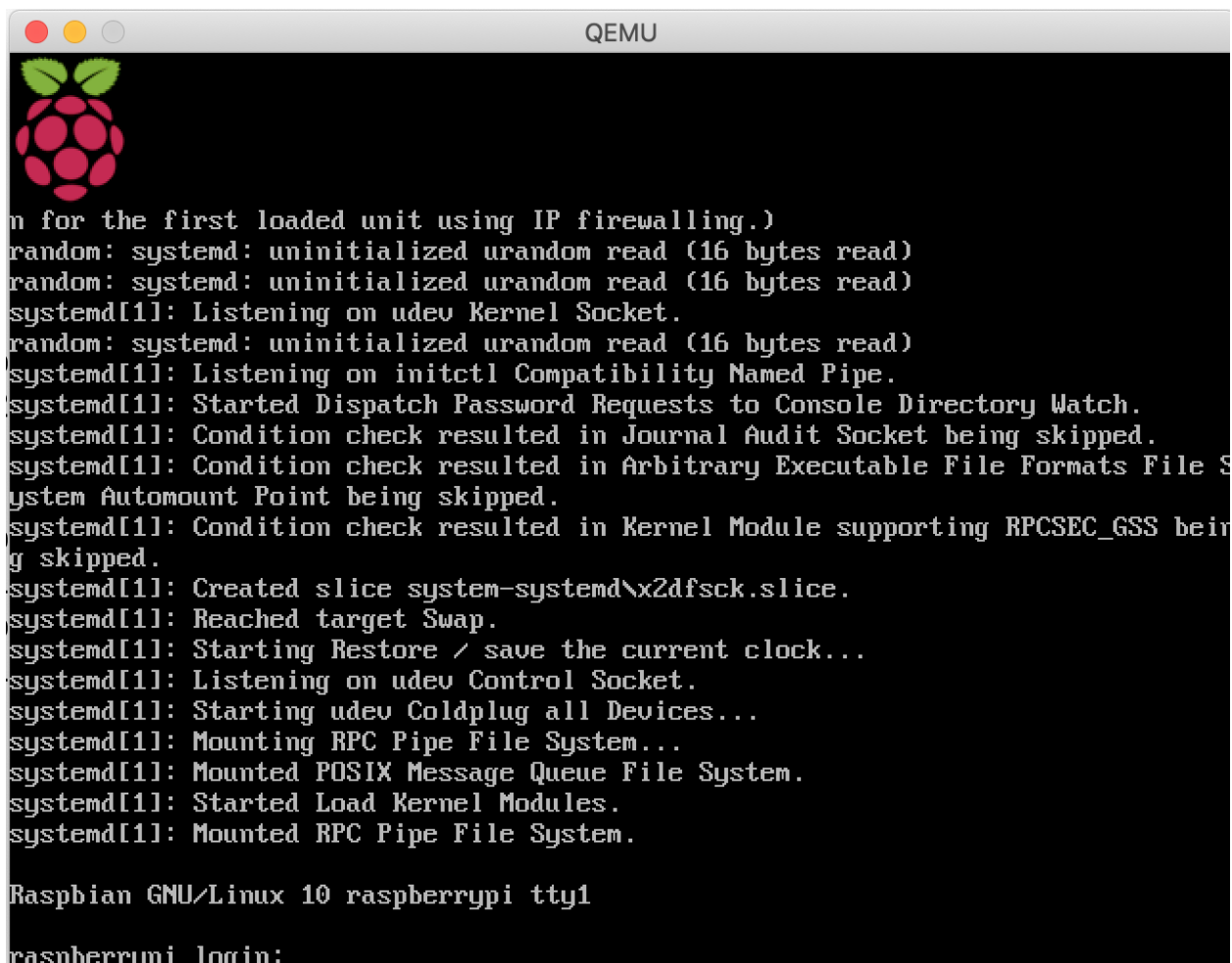
**Windows>** qemu-img convert -f raw -O qcow2 ^ 2021-01-11-raspios-buster-armhf-lite.img 2021-01.qcow2

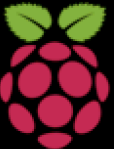
**Windows>** qemu-img resize 2021-01.qcow2 +2G

**Windows>**  
qemu-system-arm -M versatilepb ^  
-cpu arm1176 ^

```
-m 256 -hda "./2021-01.qcow2" ^  
-net nic -net user,hostfwd=tcp::5022-:22 ^  
-dtb "./versatile-pb.dtb" ^  
-kernel "./qemukernel" ^  
-append "root=/dev/sda2 panic=1 rootfstype=ext4 rw" -no-reboot ^
```

Then a new screen should pop up showing the Raspberry Pi instance booting:



```
QEMU  
  
n for the first loaded unit using IP firewalling.)  
random: systemd: uninitialized urandom read (16 bytes read)  
random: systemd: uninitialized urandom read (16 bytes read)  
systemd[1]: Listening on udev Kernel Socket.  
random: systemd: uninitialized urandom read (16 bytes read)  
systemd[1]: Listening on initctl Compatibility Named Pipe.  
systemd[1]: Started Dispatch Password Requests to Console Directory Watch.  
systemd[1]: Condition check resulted in Journal Audit Socket being skipped.  
systemd[1]: Condition check resulted in Arbitrary Executable File Formats File S  
ystem Automount Point being skipped.  
systemd[1]: Condition check resulted in Kernel Module supporting RPCSEC_GSS bein  
g skipped.  
systemd[1]: Created slice system-systemd\x2dfscck.slice.  
systemd[1]: Reached target Swap.  
systemd[1]: Starting Restore / save the current clock...  
systemd[1]: Listening on udev Control Socket.  
systemd[1]: Starting udev Coldplug all Devices...  
systemd[1]: Mounting RPC Pipe File System...  
systemd[1]: Mounted POSIX Message Queue File System.  
systemd[1]: Started Load Kernel Modules.  
systemd[1]: Mounted RPC Pipe File System.  
  
Raspbian GNU/Linux 10 raspberrypi tty1  
raspberrypi login:
```

raspberrypi login: **pi**  
raspberrypi password: **raspberry**

If your mouse cursor gets lost, then:



To shut down the Raspberry Pi gracefully, go to the Raspberry Pi's prompt and shut it down

**Raspberrypi>** sudo shutdown -h now

## EXPLANATION OF THE QEMU-SYSTEM-ARM COMMAND

**qemu-system-arm** is the executable that we use from the QEMU binaries we downloaded earlier. This is what allows us to spin up the virtual machine.

**-M versatilepb** This names the machine type for QEMU.

**-cpu arm1176** makes QEMU emulate the ARM1176 processor. This is the processor used by Raspberry Pis.

**-m 256** sets QEMU to use 256MB memory for the emulated Raspberry Pi.

**-hda "./2021-01.qcow2"** sets QEMU to use the file image 2020-12.qcow2. Qcow2 is QEMU copy-on-write format.

**-net nic -net user,hostfwd=tcp::5022-:22** The **-net nic** indicates there is a network interface card. The **"hostfwd=tcp::5022:22"** maps the host port 5022 to the raspberry pi's port 22 on the virtual machine. This allows ssh access.

**-dtb "./versatile-pb.dtb"** just maps the file we have saved in our folder to the **-M** flag we specified earlier.

**-kernel "./qemukernel"** This points QEMU to the Raspberry Pi Raspberrian kernel.

**-append "root=/dev/sda2 panic=1 rootfstype=ext4 rw"** these specifics are appended on to the boot command.

**-no-reboot** This tells QEMU to stop when the Raspberry Pi shuts down rather than rebooting on shutdown.